

PHILIP S. GREEN
Application No.: unassigned
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PATENT

forearm link of the surgical instrument relative to the pivot point.

44. The surgical system as defined in claim 41 wherein the controller is coupled to the surgical instrument by a servomechanism incorporating force feedback.

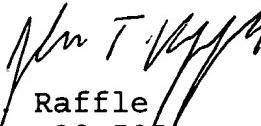
45. The surgical system as defined in claim 41 comprising a second controller, a second surgical instrument and a second servo mechanism as described such that one controller may be operated by the left hand of a surgeon and the other controller may simultaneously be operated by the right hand of the surgeon...
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REMARKS

Applicant has deleted original claims 1-25 and added new claims 26-45. Claims 26-45 are directed to the particular embodiments of servomechanism controlled surgical manipulators and controllers that are illustrated in Figs. 7-11 of the application as originally filed and described on pages 13 through 19 of the application as originally filed. The limitations of new claims 26-45 are therefore fully supported by the application as originally filed and do not contain new matter.

If the Examiner believes a telephone conference would expedite prosecution of this application, please telephone the undersigned at (415) 326-2400.

Respectfully submitted,


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